

712CD

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Original title on 712 A/B:

A Decision Support System to help Prioritize Sensor Capabilities for Lunar Landers and Planetary Rovers

If the title was revised please list the original title above and the revised title here:

WG28 & WG11

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Report Documentation Page

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A Decision Support System to help Prioritize Sensor Capabilities for Lunar Landers and Planetary Rovers

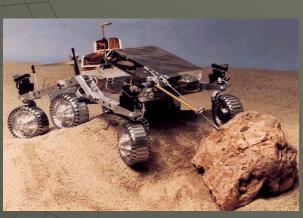






Agenda

- Background
- Initial Problem Statement
- Revised Problem Statement
- NASA's Approach
- A Value-Focused Thinking Approach
- ◆ The Decision Support System
- Additional Applications
- Conclusions

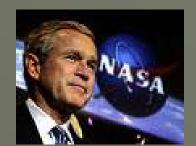






Background

President Bush's guidance:



"Our goal is to return to the moon by 2020. . . [By] establishing an extended human presence on the moon [we] could vastly reduce the costs of further space exploration, making possible even more ambitious missions."

-- January 14, 2004 address to NASA



NASA's 2006 Strategic Goals



2006 NASA

Strategic Plan

- 1. Fly the Shuttle as safely as possible until its retirement, not later than 2010
- 2. Complete the International Space Station in a manner consistent with NASA's International Partner commitments and needs of human exploration
- 3. Develop a balanced overall program of science, exploration, and aeronautics consistent with the redirection of the human spaceflight program to focus on exploration
- 4. Bring a new Crew Exploration Vehicle into service as soon as possible after Shuttle retirement
- 5. Encourage the pursuit of appropriate partnerships with the emerging commercial space sector
- 6. Establish a lunar return program having the maximum possible utility for later missions to Mars and other destinations



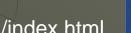
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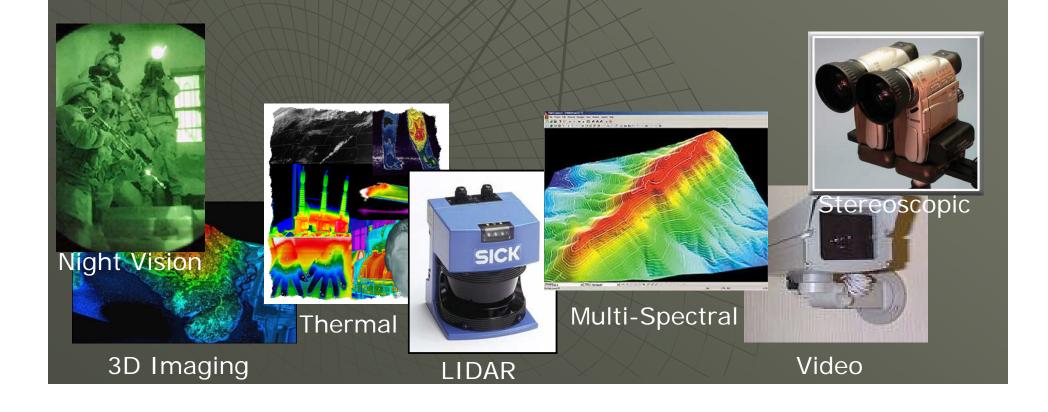
http://www.nasa.gov/mission_pages/exploration/main/index.html



Initial Problem Statement



- NASA asked us to select the best <u>sensor</u> or <u>sensor</u> <u>suites</u> to improve the safety and reliability of autonomous space exploration
- Alternative focused thinking approach





Revised Problem Statement



- Develop a decision support system to help NASA determine which sensor <u>capabilities</u> are most critical for autonomous space exploration
 - The model uses a <u>value focused approach</u> rather than an alternative focused approach
 - The model can be easily modified for varying mission requirements
 - The model segments space exploration into distinct phases in an attempt to capture overall critical mission capabilities

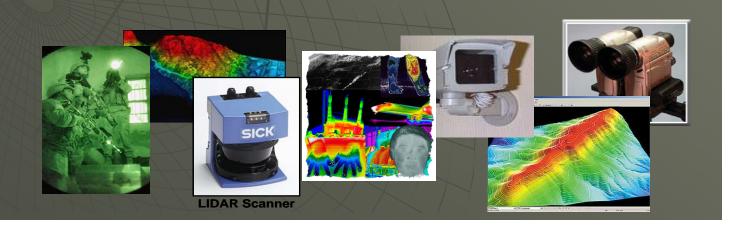




NASA's Current Approach



- Alternative Focused Thinking (AFT):
 - Focuses on existing solutions to the problem
 - Best sensor suite is limited to what is currently available on an existing list
 - Best sensor suite is also restricted by current technological capabilities
 - A one-size fits all approach that fails to reflect key requirements of any particular mission

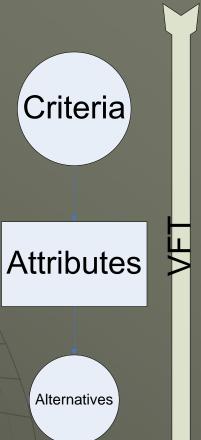




Our Team's Approach



- Value Focused Thinking (VFT)
 - Values are what people desire
 - Focuses on capabilities of an ideal sensor and the limitations the sensors have to overcome.
 - VFT is markedly different than choosing alternatives and going with the one that fits the best.
 - Focuses an organization's goals and objectives into an action plan

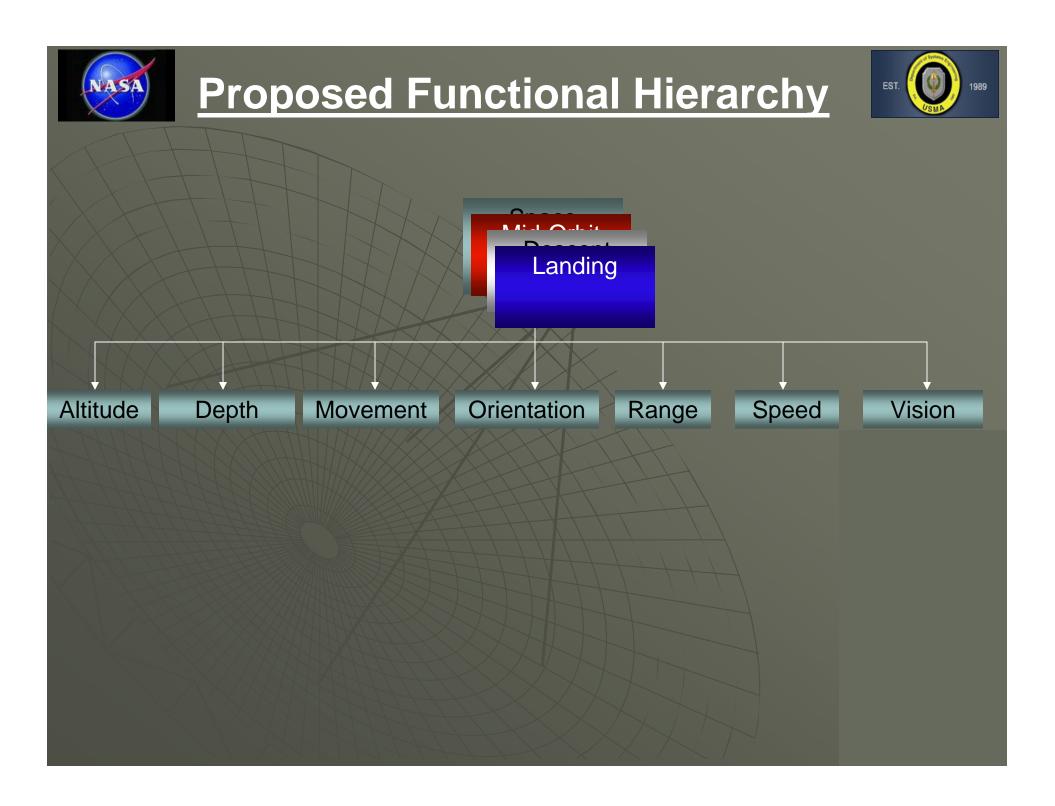




Value-Focused Thinking



- Ralph Keeney, a pioneer in the field of VFT, introduces the concept of Constraint-Free Thinking:
 - "thinking about values is constraint-free thinking . . . it is thinking about what you wish to achieve or what you wish to have."
- Provides NASA with a new approach to its research, development and design process
- Provides NASA with a more unconstrained view of examining what sensor capabilities and requirements it values as being the most critical for future missions

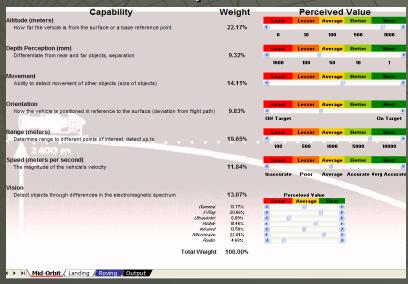




Our Decision Support Model



- A MS Excel Decision Support System (DSS)
 - Makes decisions easier for the stakeholders
 - Links strategy with research
- Breaks a space mission down into 3 distinct phases: mid-orbit, descent, landing
- Flexible tool that can be tailored, customized, and adapted to various issues





Demo of the Model



Capability			Perceived Value				
ltitude (meters)	_	Least	Lesser	Average	Better	Best	
How far the vehicle is from the surface or a base reference point		₹					
		0	10	100	500	1000	
epth Perception (mm)	9.32%	Least	Lesser	Average	Better	Best	
Differentiate from near and far objects, separation		1000	100	50	10	1	
Movement		Least	Lesser	Average	Better	Best	
Ability to detect movement of other objects (size of objects)		<u>(1)</u>					
rientation		Least	Lesser	Average	Better	Best	
How the vehicle is positioned in reference to the surface (deviation from flight path)		(1)		0)			
		Off Target				On Targe	
ange (meters)		Least	Lesser	Average	Better	Best	
Determine range to different points of interest, detect up to		₹					
27400 m	19.65%	100	500	1000	5000	10000	
peed (meters per second)		Least	Lesser	Average	Better	Best	
The magnitude of the vehicle's velocity		₹	LUJJU	Titelage	Detter		
		Inaccurate	Poor	Average	Accurate	Very Accur	
ision							
Detect objects through differences in the electromagnetic spectrum		Perceived Value					
		Least	Average				
Gamma X-Ray	13.77% 20.66%	₹					
N-May Ultraviolet	6.89%	4		>			
Visible	18.46%	•					
Infrared	13.50%	4		>			
Microwave	22.04%	1					
Radio	4.68%	«		>			
	100.00%						



Additional Applications



- Easily modified for various applications
- Marine Corps Combat Development Command (MCCDC)
 - Approx. \$20K for a 3rd party to develop a similar product for a Marine Corps Personnel Carrier



Additional Applications

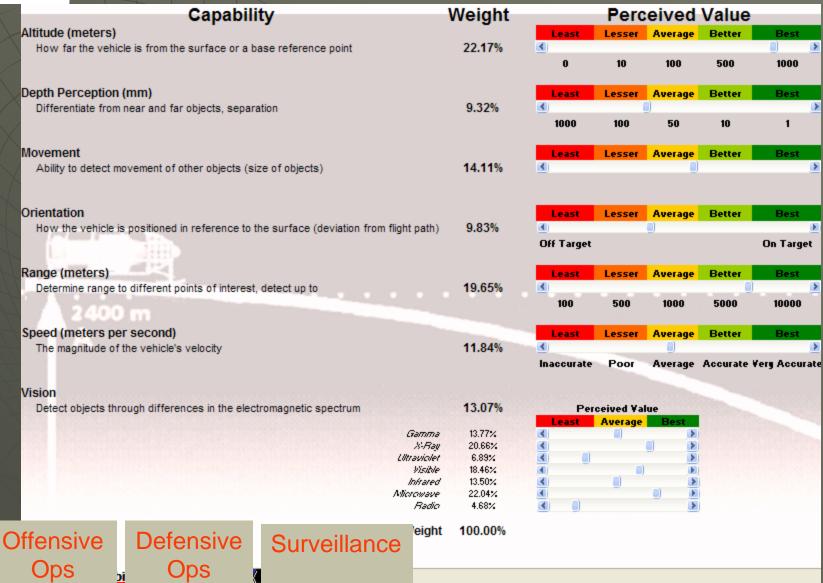


- Future Weapons Systems
 - Unmanned Ground Vehicle
 - Similar to NASA's rovers





Additional Applications





Conclusions



- Help identify capabilities and close the gaps for the organization
- Helps direct R&D funding, more focused approach
- Provided our stakeholder with a different approach to their problem (value focused as compared to alternative focused)
- Multi-phase approach vs. single static approach
- Flexible tool that has multiple applications
- Sensitivity Analysis
 - Next step in the project



Documentation



- http://www.nasa.gov/mission_pages /exploration/main/index.html
- Ralph L. Keeney. (1992). Value-Focused Thinking. Massachusetts: Harvard University Press.
- Google Images
- Discovery Channel Future Weapon Systems